

## SDNL105 - transitory Under-structuring nonlinear: shock of 3 beams between them

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### Summary:

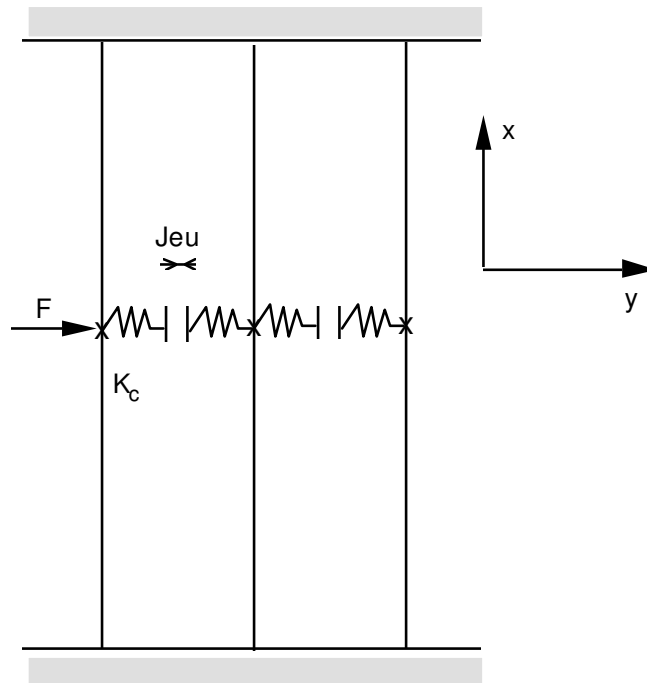
The scope of application of this test relates to the dynamics of the structures, and more particularly the calculation of transitory answer nonlinear per dynamic under-structuring.

It is a question of calculating the nonlinear transitory response of 3 beams in inflection with shocks to the center of the beams. The beams are modelled by elements of the type `POU_D_E` (model of Euler).

The results of reference result from a direct transitory calculation by modal recombination. This test thus makes it possible to validate the computational tools of response transitory by under - structuring, in the case of the taking into account of non-linearities of type shock between mobile structures.

## 1 Problem of reference

### 1.1 Geometry



The length of the beams is worth:  $L = 1\text{ m}$

The beams are of circular section:

- of ray:  $R = 0.1\text{ m}$
- of thickness:  $ep = 0.01\text{ m}$

The game between the beams is worth:  $Jeu = 1\ 10^{-3}\text{ m}$

### 1.2 Material properties

$$E = 1.10^{10}\text{ Pa}$$

$$\nu = 0.3$$

$$\rho = 1.10^8\text{ kg/m}^3$$

The stiffness within the competence of contact is worth:  $K_c = 1.10^8\text{ N/m}$

### 1.3 Boundary conditions and loadings

On all the structure:  $DX = DZ = DRX = DRY = 0$ .

With the ends superior and inferior of the beams:  $DY = DRZ = 0$ .

In the middle of the beam of left: as from the moment  $t = 0\text{ s}$ ,  $Fy = -1.10^6\text{ N}$

### 1.4 Initial conditions

Structure initially at rest.

## 2 Reference solution

### 2.1 Method of calculating used for the reference solution

The reference solution is given by a direct transitory calculation by modal superposition (modeling A).

### 2.2 Results of reference

Value displacements and speed of the nodes of the 3 beams according to the direction  $Y$  and at the moment  $t = 1 s$ .

	Displacement ( m )	Speed ( $m.s^{-1}$ )
Diagram of integration of Euler		
Beam of left	$1.64 \cdot 10^{-2}$	$2.54 \cdot 10^{-2}$
Beam medium	$1.12 \cdot 10^{-2}$	$4.49 \cdot 10^{-2}$
Beam of right-hand side	$5.90 \cdot 10^{-3}$	$1.05 \cdot 10^{-1}$
Diagram of integration of Devogelaere		
Beam of left	$1.64 \cdot 10^{-2}$	$2.54 \cdot 10^{-2}$
Beam medium	$1.12 \cdot 10^{-2}$	$4.41 \cdot 10^{-2}$
Beam of right-hand side	$5.89 \cdot 10^{-3}$	$1.05 \cdot 10^{-1}$
Diagram of integration to step of adaptive time of order 2		
Beam of left	$1.64 \cdot 10^{-2}$	$2.55 \cdot 10^{-2}$
Beam medium	$1.12 \cdot 10^{-2}$	$4.41 \cdot 10^{-2}$
Beam of right-hand side	$5.91 \cdot 10^{-3}$	$1.05 \cdot 10^{-1}$

### 2.3 Uncertainty on the solution

Digital solution.

## 3 Modeling A

### 3.1 Characteristics of modeling

The beam is with a grid in segments to which are affected of the elements of the type `POU_D_E`.

With the transitory problem dealt, project on the basis of clean mode the first 15 of the structure, is solved directly by the transitory operator of calculation by modal recombination.

### 3.2 Characteristics of the grid

Many nodes: 41

Many meshes and types: 42 `SEG2`

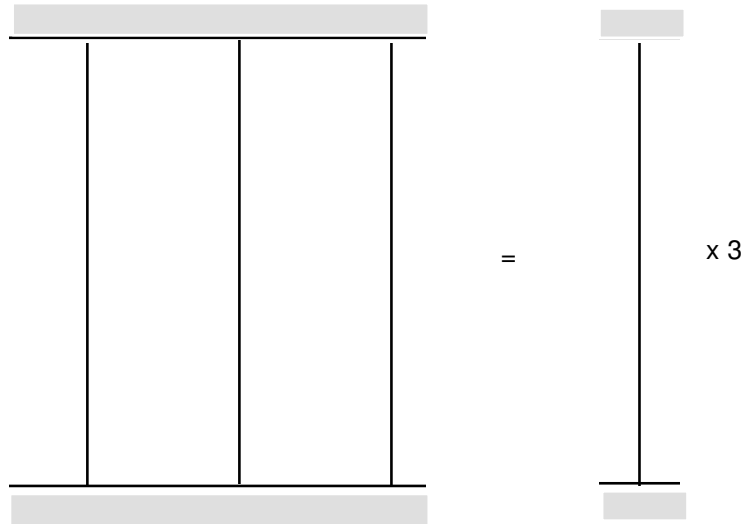
### 3.3 Actual values: reference for modeling B

Identification	Aster
Diagram of integration of Euler	
Beam of left: Displacement ( <i>m</i> )	1.64 10 <sup>-2</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	2.54 10 <sup>-2</sup>
Beam of medium: Displacement ( <i>m</i> )	1.12 10 <sup>-2</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	4.43 10 <sup>-2</sup>
Beam of right-hand side: Displacement ( <i>m</i> )	5.90 10 <sup>-3</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	1.05 10 <sup>-1</sup>
Diagram of integration of Devogelaere	
Beam of left: Displacement ( <i>m</i> )	1.64 10 <sup>-2</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	2.54 10 <sup>-2</sup>
Beam of medium: Displacement ( <i>m</i> )	1.12 10 <sup>-2</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	4.41 10 <sup>-2</sup>
Beam of right-hand side: Displacement ( <i>m</i> )	5.89 10 <sup>-3</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	1.05 10 <sup>-1</sup>
Diagram of integration to step of adaptive time of order 2	
Beam of left: Displacement ( <i>m</i> )	1.64 10 <sup>-2</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	2.55 10 <sup>-2</sup>
Beam of medium: Displacement ( <i>m</i> )	1.12 10 <sup>-2</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	4.41 10 <sup>-2</sup>
Beam of right-hand side: Displacement ( <i>m</i> )	5.91 10 <sup>-3</sup>
Speed ( <i>m.s</i> <sup>-1</sup> )	1.05 10 <sup>-1</sup>

## 4 Modeling B

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### 4.1 Characteristics of modeling



The dynamic under-structuring makes it possible to calculate the vibratory behavior of the 3 beams starting from the dynamic characteristics of only one beam. This one is with a grid in segments to which are affected of the elements of the type `POU_D_E`.

The structure is studied using the method of under-structuring with interfaces of the type "Craig - Bampton" (blocked interfaces).

The base of the first 15 clean modes of the complete structure is calculated by under-structuring. Then the transitory problem, project on this basis, is solved by the transitory operator of calculation by modal recombination.

### 4.2 Characteristics of the grid

Many nodes: 15

Many meshes and types: 14 `SEG2`

## 4.3 Sizes tested and results

Identification	Reference	Aster	% difference
Diagram of integration of Euler			
Beam of left: Displacement ( $m$ )	$1.64 \cdot 10^{-2}$	$1.64 \cdot 10^{-2}$	
Speed ( $m.s^{-1}$ )	$2.54 \cdot 10^{-2}$	$2.54 \cdot 10^{-2}$	
Beam of medium: Displacement ( $m$ )	$1.12 \cdot 10^{-2}$	$1.12 \cdot 10^{-2}$	< 0.01%
Speed ( $m.s^{-1}$ )	$4.43 \cdot 10^{-2}$	$4.43 \cdot 10^{-2}$	
Beam of right-hand side: Displacement ( $m$ )	$5.90 \cdot 10^{-3}$	$5.90 \cdot 10^{-3}$	
Speed ( $m.s^{-1}$ )	$1.05 \cdot 10^{-1}$	$1.05 \cdot 10^{-1}$	
Diagram of integration of Devogelaere			
Beam of left: Displacement ( $m$ )	$1.64 \cdot 10^{-2}$	$1.64 \cdot 10^{-2}$	
Speed ( $m.s^{-1}$ )	$2.54 \cdot 10^{-2}$	$2.54 \cdot 10^{-2}$	
Beam of medium: Displacement ( $m$ )	$1.12 \cdot 10^{-2}$	$1.12 \cdot 10^{-2}$	< 0.01%
Speed ( $m.s^{-1}$ )	$4.41 \cdot 10^{-2}$	$4.41 \cdot 10^{-2}$	
Beam of right-hand side: Displacement ( $m$ )	$5.89 \cdot 10^{-3}$	$5.89 \cdot 10^{-3}$	
Speed ( $m.s^{-1}$ )	$1.05 \cdot 10^{-1}$	$1.05 \cdot 10^{-1}$	
Diagram of integration to step of adaptive time of order 2			
Beam of left: Displacement ( $m$ )	$1.64 \cdot 10^{-2}$	$1.64 \cdot 10^{-2}$	
Speed ( $m.s^{-1}$ )	$2.55 \cdot 10^{-2}$	$2.55 \cdot 10^{-2}$	
Beam of medium: Displacement ( $m$ )	$1.12 \cdot 10^{-2}$	$1.12 \cdot 10^{-2}$	< 0.01%
Speed ( $m.s^{-1}$ )	$4.41 \cdot 10^{-2}$	$4.41 \cdot 10^{-2}$	
Beam of right-hand side: Displacement ( $m$ )	$5.91 \cdot 10^{-3}$	$5.91 \cdot 10^{-3}$	
Speed ( $m.s^{-1}$ )	$1.05 \cdot 10^{-1}$	$1.05 \cdot 10^{-1}$	

## 5 Summary of the results

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Precision on displacements and speeds of the nodes mediums of the 3 beams at the moment  $t = 1\text{ s}$  is excellent (relative error  $< 0.01\text{ s}$ ).

This test thus validates the operators of non-linear transitory calculation by dynamic under-structuring.