

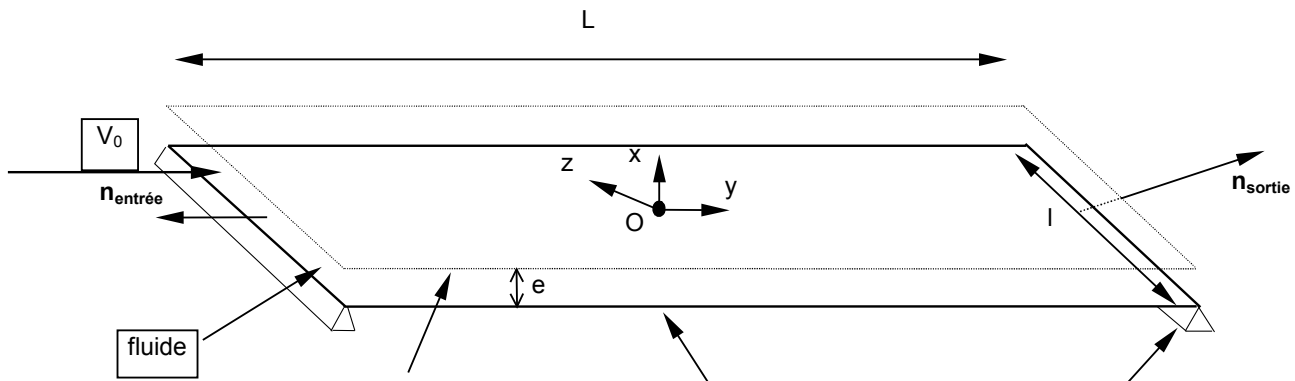
FDLV109 - Computation of coefficients added out of Summarized plane

flow:

This test of the fluid field/structure implements the computation of mass, stiffness and damping added on a plane structure subjected to a confined flow which one supposes potential. These added coefficients are calculated for a velocity upstream of 4 m.s^{-1} , on a model 3D for the fluid and shell for structure. The structure is subjected to an imposed displacement of bending.

1 Problem of reference

1.1 Geometry



$$L = 50 \text{ m}$$

$$I = 5 \text{ m}$$

thickness of fluid $e = 0.5 \text{ m}$

thickness of the plate $h = 0.5 \text{ m}$

the reference $Oxyz$ is at a distance from $\frac{e}{2}$ plate

1.2 Properties of the materials

Fluid: density $\rho = 1000 \text{ kg.m}^{-3}$ (water).

Structure: $\rho_s = 7800 \text{ kg/m}^3$; $E = 2.1 \cdot 10^{11} \text{ Pa}$; $\nu = 0.3$ (steel).

1.3 Boundary conditions and loadings

Fluid:

- to simulate steady flow, one forces on the face of entry of the fluid a normal velocity of -4 m/s (by thermal analysis, one imposes a normal heat flux are equivalent of -4),
- to compute: the fluid disturbance brought by the motion of the external cylinder one imposes a boundary condition of Dirichlet in a node of the fluid.

- one imposes in $x = \frac{e}{2}$ the condition $\varphi_1 = \varphi_2 = 0$ which corresponds to a null flow through the higher fluid wall.

Structure:

- the plate is subjected to a displacement corresponding to its first two modes of bending [bib2]:

$$X_1 = \sin \frac{\pi y}{L} ; X_2 = \sin \frac{2\pi y}{L}$$

2 Reference solution

2.1 Method of calculating used for the reference solution

For computation of the added coefficients:

one shows [bib1] that the coefficients of mass and added depreciation depend on the permanent potential fluid velocities $\bar{\phi}$ as well as two fluctuating potentials ϕ_1 and ϕ_2 : these potentials are in the case of written the motion of bending of the plate [bib1]:

$$\text{For the first mode: } \begin{cases} \bar{\phi}^{(1)} = V_0 y \\ \phi_1^{(1)} = \left(x - \frac{e}{2}\right) \sin \frac{\pi y}{L} \\ \phi_2^{(1)} = \frac{V_0 \pi}{L} \left(x - \frac{e}{2}\right) \cos \frac{\pi y}{L} \end{cases}$$

$$\text{For the second mode: } \begin{cases} \bar{\phi}^{(2)} = V_0 y \\ \phi_1^{(2)} = \left(x - \frac{e}{2}\right) \sin \frac{2\pi y}{L} \\ \phi_2^{(2)} = \frac{2V_0 \pi}{L} \left(x - \frac{e}{2}\right) \cos \frac{2\pi y}{L} \end{cases}$$

However the added modal coefficients projected on these modes of bending are written:

$$\begin{aligned} M_{ij}^a &= \rho \int_{\text{cylindre externe}} \phi_1^{(i)} \mathbf{X}_j \cdot \mathbf{n} \, dS \\ C_{ij}^a &= \rho \int_{\text{cylindre externe}} \left(\phi_2^{(i)} + \nabla \bar{\phi}^{(i)} \cdot \nabla \phi_1^{(i)} \right) \left(\mathbf{X}_j \cdot \mathbf{n} \right) \, dS \\ K_{ij}^a &= \rho \int_{\text{cylindre externe}} \left(\nabla \bar{\phi}^{(i)} \cdot \nabla \phi_2^{(i)} \right) \left(\mathbf{X}_j \cdot \mathbf{n} \right) \, dS \end{aligned}$$

that is to say:

$$\begin{aligned} M_{11}^a &= M_{22}^a = \rho e l \frac{L}{2} \quad ; \quad M_{12}^a = 0 \\ C_{11}^a &= C_{22}^a = 0 \quad ; \quad C_{12}^a = C_{21}^a = -\frac{8}{3} \rho e l V_0 \\ K_{11}^a &= -\rho e V_0^2 \frac{\pi^2 l}{2L} \quad ; \quad K_{22}^a = -\rho e V_0^2 \frac{2\pi^2 l}{L} \quad ; \quad K_{12}^a = 0 \end{aligned}$$

•Numerical applications:

One did a calculation of added damping which corresponds for the velocity given to a deadened vibratory behavior of structure:

velocity V_0 with 4 m.s^{-1}

the values of the mechanical system are:

$$e = h = 5.10^{-1} \text{ m} \quad L = 50 \text{ m} \quad l = 5 \text{ m}$$

The added mass brought by flow is worth:

$$M_{11}^a = 0.625 \cdot 10^5 \text{ kg}$$

$$M_{22}^a = 0.625 \cdot 10^5 \text{ kg}$$

$$M_{12}^a = 0$$

The damping added is worth with $V_0 = 4 \text{ m.s}^{-1}$:

$$C_{11}^a = 0$$

$$C_{22}^a = 0$$

$$C_{12}^a = 0.266 \cdot 10^5 \text{ N.m}^{-1}$$

The added stiffness is worth with $V_0 = 4 \text{ m.s}^{-1}$:

$$K_{11}^a = -0.3943 \cdot 10^4 \text{ N.m}^{-1} \text{ rad}^2$$

$$K_{22}^a = -0.1577 \cdot 10^5 \text{ N.m}^{-1} \text{ rad}^2$$

$$K_{12}^a = 0$$

2.2 Results of reference

Result analytical.

2.3 References bibliographical

- ROUSSEAU G., LUU H.T. : Mass, damping and stiffness added for a vibrating structure placed in a potential flow - Bibliography and establishment in *the Code_Aster* - HP-61/95/064
- BLEVINS R.D: Formulated for natural frequency and shape mode. ED. Krieger 1984

3 Modelization A

3.1 Characteristic of the modelization

For the system 3D on which one calculates the added coefficients:

For solid: 160 meshes QUAD4
shell elements MEDKQU4

For the fluid: 160 meshes QUAD4
elements thermal THER_FACE4
on the plane surface

184 meshes thermal
QUAD4 elements THER_FACE4
on the sides of entry and output of fluid volume

480 meshes thermal
HEXA8 elements THER_HEXAS
in fluid volume

3.2 Values tested

Identification	Reference
M_{11}^a	0.625 105
M_{22}^a	0.625 105
M_{12}^a	0
C_{11}^a	0
C_{22}^a	0
C_{12}^a	0.266 105
K_{11}^a	- 0.394 104
K_{22}^a	- 0.157 105
K_{12}^a	0

4 Summary of the results

the computational tool of coefficients added under flow (potential assumption) were validated on the first two modes of bending of a plane structure. It is necessary however to note [bib1] that the very good agreement between the model semi-analytical proposed for comparison and numerical computation are obtained only if the plate is sufficiently long, the model semi-analytical being makes of it only one approximate solution of the posed problem.