
Structure of data sd_macr_elem_dyna

Summary:

The structure of data sd_macr_elem_dyna contains the projection of the matrices of rigidity, mass and possibly of damping of a substructure on a beforehand definite basis.
It also contains the projection of the loading if one applies a loading to the substructure.

That structure of data is used for calculations of dynamic under-structuring. The dynamic macronutrient creates can also be used as super-mesh in a mixed model.

Contents

Contents

1 General information.....	3
2 Tree structure of the Structure of Data.....	3
3 Contents of the objects.....	3
3.1 Object .DESM.....	3
3.2 Object .REFM.....	4
3.3 Object .LINO.....	4
3.4 Object .CONX.....	4
3.5 Object .MAEL_DESC.....	4
3.6 Object .MAEL_REFE.....	4
3.7 Object .LICH.....	4
3.8 Object .LICA.....	5
3.9 Object .MAEL_RAID_DESC.....	5
3.10 Object .MAEL_RAID_REFE.....	5
3.11 Object .MAEL_RAID_VALE.....	5
3.12 Object .MAEL_MASS_DESC.....	5
3.13 Object .MAEL_MASS_REFE.....	5
3.14 Object .MAEL_MASS_VALE.....	6
3.15 Object .MAEL_AMOR_DESC.....	6
3.16 Object .MAEL_AMOR_REFE.....	6
3.17 Object .MAEL_AMOR_VALE.....	6
3.18 Object .MAEL_INER_REFE.....	6
3.19 Object .MAEL_INER_VALE.....	6
3.20 Classification of the basic vectors.....	7

1 General information

The structure of data `sd_macr_elem_dyna` contains the projection of the matrices of rigidity, mass and possibly of damping of a substructure on a beforehand selected basis.

It also contains the projection of the loading if one applies a loading to the substructure.

A structure of data `sd_nume_ddl` is attached to the structure of data `sd_macr_elem_dyna`. One referred there for the fictitious classification of the basic vectors of projection.

In order to ensure compatibility with `sd_macr_elem_stat`, data are repeated in various objects of the structure of data.

This structure of data is used in calculations of dynamic under-structuring or calculations with a mixed modeling. In this case, the dynamic macronutrient is used as super-mesh of the model.

2 Tree structure of the Structure of Data

```
sd_macr_elem_dyna (K8):: = record

    % description of the dynamic substructure
    ♦      \.DESM'           :   OJB   S   V   I
    ♦      \.REFM'           :   OJB   S   V   K8
    ♦      \.CONX'           :   OJB   S   V   I
    ♦      \.LINO'           :   OJB   S   V   I
    ♦      \.MAEL_DESC'      :   OJB   S   V   I
    ♦      \.MAEL_REFE'      :   OJB   S   V   K24
    % description of the loadings
    ◊      \.LICH'           :   OJB   XC  V   K8  NO
    ◊      \.LICA'           :   OJB   XD  V   R   NO
    % projected rigidity
    ♦      \.MAEL_RAID_DESC' :   OJB   S   V   I
    ♦      \.MAEL_RAID_REFE' :   OJB   S   V   K24
    ♦      \.MAEL_RAID_VALE' :   OJB   S   V   R or C
    % masses projected
    ♦      \.MAEL_MASS_DESC' :   OJB   S   V   I
    ♦      \.MAEL_MASS_REFE' :   OJB   S   V   K24
    ♦      \.MAEL_MASS_VALE' :   OJB   S   V   R
    % damping project
    ◊      \.MAEL_AMOR_DESC' :   OJB   S   V   I
    ◊      \.MAEL_AMOR_REFE' :   OJB   S   V   K24
    ◊      \.MAEL_AMOR_VALE' :   OJB   S   V   R
    % inertias following DX, DY and DZ
    ◊      \.MAEL_INER_REFE' :   OJB   S   V   K24
    ◊      \.MAEL_INER_VALE' :   OJB   S   V   R
    % classification of the basic vectors
    ♦      \$.VIDE'          :   sd_nume_ddl
```

3 Contents of the objects

3.1 Object `.DESM`

```
\.DESM'           :   OJB   S   V   I           length = 10
  DESM (1) : 0
  DESM (2) : nbnstc (many nodes used for the classification of the basic vectors)
  DESM (3) : many internal nodes of the substructure
```

DESM (4) : nbvect (many basic vectors)
DESM (5) : 0
DESM (6) : 0
DESM (7) : many loadings
DESM (8) with DESM (10) : 0

3.2 Object .REFM

```
\.REFM'           : OJB   S   V   K8   length = 8  
REFM (1) : name of the model  
REFM (2) : name of the grid  
REFM (3) : field material  
REFM (4) : elementary characteristics  
REFM (5) : name of the dynamic macronutrient  
REFM (6) : 'OUI_RIGI'  
REFM (7) : 'OUI_MASS'  
REFM (8) : 'OUI_AMOR' / 'NON_AMOR'
```

3.3 Object .LINO

```
\.LINO'           : OJB   S   V   I   length = nbnstc
```

List of the numbers of the nodes used for the classification of the basic vectors

3.4 Object .CONX

```
\.CONX'           : OJB   S   V   I   length = 3*nbnstc
```

For I varying 1 with nbnstc :

```
CONX (3* (i-1) +1) : 1  
CONX (3* (i-1) +2) : LINO (I)  
CONX (3* (i-1) +3) : 0  
...
```

3.5 Object .MAEL_DESC

```
\.MAEL_DESC'      : OJB   S   V   I   length = 3  
MAEL_DESC (1) : many coded entreties necessary to the size DEPL_R  
MAEL_DESC (2) : component count maximum for the size DEPL_R  
MAEL_DESC (3) : number of the size DEPL_R in the catalogue of the sizes
```

3.6 Object .MAEL_REFE

```
\.MAEL_REFE'      : OJB   S   V   K24  length = 2  
MAEL_REFE (1) : name of the base of projection  $\Phi$   
MAEL_REFE (2) : name of the grid
```

3.7 Object .LICH

This object is created only if one applies a loading to the substructure.

```
\.LICH'           : OJB   XC  V   K8  NO
```

This collection contains the names of the loadings.

LICH (I) is of dimension 2.

In the case of load number I, one a:

LICH (I) (1) : 'NON_SUIV'

LICH (I) (2) : name of the generalized loading F_i

3.8 Object .LICA

This object is created only if one applies a loading to the substructure.

`.LICA' : OJB XD V R NO

This collection contains the generalized coordinates of the loadings.

LICA (I) is of dimension $2*nbvect$

Each object is made of two end to end stored identical segments.

In each segment, one finds the loadings generalized: $f_i = \Phi^T F_i$

3.9 Object .MAEL_RAID_DESC

`.MAEL_RAID_DESC' : OJB S V I length = 3

MAEL_RAID_DESC (1) : 2

MAEL_RAID_DESC (2) : nbvect

MAEL_RAID_DESC (3) : 2

3.10 Object .MAEL_RAID_REFE

`.MAEL_RAID_REFE' : OJB S V K24 length = 2

MAEL_RAID_REFE (1) : name of the base of projection Φ

MAEL_RAID_REFE (2) : vacuum if one exploits the matrix of impedance of the ground, or the name of the matrix of rigidity K to project

3.11 Object .MAEL_RAID_VALE

`.MAEL_RAID_VALE' : OJB S V R or C length = nbvect* (nbvect+1)/2

This object contains the matrix of projected rigidity $\tilde{K} = \Phi^T K \Phi$

This matrix is symmetrical, one stores only the higher triangular block.

3.12 Object .MAEL_MASS_DESC

`.MAEL_MASS_DESC' : OJB S V I length = 3

MAEL_MASS_DESC (1) : 2

MAEL_MASS_DESC (2) : nbvect

MAEL_MASS_DESC (3) : 2

3.13 Object .MAEL_MASS_REFE

`.MAEL_MASS_REFE' : OJB S V K24 length = 2

MAEL_MASS_REFE (1) : name of the base of projection Φ

MAEL_MASS_REFE (2) : vacuum or name of the matrix of mass M to project

3.14 Object .MAEL_MASS_VALE

\.MAEL_MASS_VALE' : OJB S V R length = nbvect* (nbvect+1)/2

This object contains the matrix of projected mass $\tilde{M} = \Phi^T M \Phi$

Only the higher triangular block is stored.

3.15 Object .MAEL_AMOR_DESC

\.MAEL_AMOR_DESC' : OJB S V I length = 3
MAEL_AMOR_DESC (1) : 2
MAEL_AMOR_DESC (2) : nbvect
MAEL_AMOR_DESC (3) : 2

3.16 Object .MAEL_AMOR_REFE

\.MAEL_AMOR_REFE' : OJB S V K24 length = 2
MAEL_AMOR_REFE (1) : name of the base of projection Φ
MAEL_AMOR_REFE (2) : vacuum or the name of the matrix of damping C to project

3.17 Object .MAEL_AMOR_VALE

\.MAEL_AMOR_VALE' : OJB S V R length = nbvect* (nbvect+1)/2

This object contains the terms of the matrix of damping projected (triangular higher)

$$\tilde{C} = \Phi^T C \Phi$$

If the user provides the generalized depreciation associated with the dynamic modes, the diagonal terms of this matrix contain provided depreciation.

3.18 Object .MAEL_INER_REFE

This object is not creates if the matrix of impedance of the ground is exploited.

\.MAEL_INER_REFE' : OJB S V K24 length = 2
MAEL_INER_REFE (1) : name of the base of projection Φ
MAEL_INER_REFE (2) : name of the matrix of inertia M used for the calculation of inertias

3.19 Object .MAEL_INER_VALE

This object is not creates if the matrix of impedance of the ground is exploited.

\.MAEL_INER_VALE' : OJB S V R length = 3*nbvect

This object contains inertias along the axes DX, DY and DZ

MAEL_INER_VALE (1) with MAEL_INER_VALE (nbvect) : inertia according to DX
where: MAEL_INER_VALE (I) : $(L_x \Phi_i)^T M (L_x \Phi_i)$

MAEL_INER_VALE (nbvect+1) with MAEL_INER_VALE (2*nbvect) : inertia according to DY

where: MAEL_INER_VALE (nbvect+i) : $(L_y \Phi_i)^T M (L_y \Phi_i)$

MAEL_INER_VALE (2*nbvect+1) with MAEL_INER_VALE (3*nbvect) : inertia according to DZ
where: MAEL_INER_VALE (2*nbvect+i) : $(L_z \Phi_i)^T M (L_z \Phi_i)$

L_x indicate a matrix of localization of which the columns are made up of 1 on the ddl DX and 0 elsewhere.

L_y indicate a matrix of localization of which the columns are made up of 1 on the ddl DY and 0 elsewhere.

L_z indicate a matrix of localization of which the columns are made up of 1 on the ddl DZ and 0 elsewhere.

Φ_i indicate the 2rd vector of the base of projection.

3.20 Classification of the basic vectors

A structure of data sd_numd_ddl is attached to the structure of data sd_macr_elem_dyna. One refers to it for the classification of the basic vectors.