

## Algorithm of linear thermics transitory

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### Summary:

One presents the algorithm of transitory thermics linear established within the order `THER_LINEAIRE` [U4.33.01]. The various options of calculation necessary were presented in the elements of structure plans, axisymmetric and three-dimensional [U1.22.01], [U1.23.01] and [U1.24.01].

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## Contents

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1 Expression of the equation of heat in linear thermics.....	3
1.1 Equation of heat.....	3
1.2 Fourier analysis.....	3
1.3 Equation of heat in the case of the linear model of thermics.....	3
2 Boundary conditions, loading and initial condition.....	4
2.1 Imposed temperatures.....	4
2.2 Linear relations.....	4
2.3 Imposed normal flow.....	4
2.4 Exchange.....	5
2.5 Wall exchange.....	5
2.6 Voluminal source.....	5
2.7 Initial condition.....	5
3 Variational formulation of the problem.....	6
4 Variational formulation of the problem with condition of exchange between two walls.....	6
5 Discretization in time of the differential equation.....	7
5.1.1 Precision of the method.....	7
5.1.2 Stability of the method.....	8
5.1.3 Application to the equation of heat.....	9
6 Space discretization.....	10
7 Implementation in Code_Aster.....	11
7.1 Introduced equations.....	11
7.2 Principal thermal options calculated in Code_Aster.....	12
7.2.1 Boundary conditions and loadings.....	12
7.2.2 Calculation of the elementary matrices and transitory term.....	12
8 Description of the versions of the document.....	12

## 1 Expression of the equation of heat in linear thermics

### 1.1 Equation of heat

One places oneself in open  $\Omega$  of  $\mathbb{R}^3$  of regular border  $\Gamma$ .  
In any point of  $\Omega$ , the equation of heat can be written:

$$-\operatorname{div}(\mathbf{q}(r, t)) + s(r, t) = \rho C_p \frac{\partial T(r, t)}{\partial t}$$

with:

$\mathbf{q}$	vector heat flow (directed according to the decreasing temperatures),
$s$	heat per unit of volume dissipated by the internal sources,
$\rho C_p$	voluminal heat with constant pressure,
$T$	temperature,
$r$	variable of space,
$t$	variable time.

This equation translates the phenomenon of change of the temperature (only through the phenomenon of diffusion, convection having been neglected) into any point of opened and at any moment. She admits in theory an infinity of solutions, but the data of the initial conditions and the variation of the boundary conditions in the course of time determines the evolution of the phenomenon perfectly.

### 1.2 Fourier analysis

In thermal conduction, the Fourier analysis provides an equation connecting the heat flow to the gradient of the temperature (normal vector on the isothermal surface). This law reveals, in its most general form, a tensor of conductivity. In the case of an isotropic material, this tensor is reduced to a simple coefficient  $\lambda$ , the thermal coefficient of conductivity.

$$\mathbf{q}(r, t) = -\lambda \nabla T(r, t)$$

For the elements of anisotropic thermics one will refer to Establishment of the elements 2D and 2D-Axisymmetric in mechanics and thermics [R3.06.02].

### 1.3 Equation of heat in the case of the linear model of thermics

By combining the two equations above, one obtains:

$$-\operatorname{div}(-\lambda \nabla T(r, t)) + s(r, t) = \rho C_p \frac{\partial T(r, t)}{\partial t}$$

## 2 Boundary conditions, loading and initial condition

One describes here only the boundary conditions thermal leading to linear equations in temperature, which excludes the conditions of type radiation.

### 2.1 Imposed temperatures

The conditions of the Dirichlet type, are usually treated by dualisation in *Code\_Aster* (cf [R3.03.01]), but they can also be eliminated in certain cases (loads kinematics).

$$T(r, t) = T_1(r, t) \quad \text{sur } \Gamma_1$$

where  $T_1(r, t)$  is a function of the variable of space and/or time.

### 2.2 Linear relations

It is of the conditions of the Dirichlet type, making it possible to define a linear relation between the values of the temperature:

- between two or several nodes: with an equation of the form

$$\sum_{i=1}^n \alpha_i T_i(r, t) = \beta(t)$$

- between couples of nodes: with an equation of the form

$$\sum_{i=1}^{n_1} \alpha_{1i} T_{i/\Gamma_{12}}(r, t) + \sum_{i=1}^{n_2} \alpha_{2i} T_{i/\Gamma_{21}}(r, t) = \beta(t)$$

where  $\Gamma_{12}$  and  $\Gamma_{21}$  are two under-parts of the border which one binds two to two the values of the temperature. This kind of boundary condition makes it possible to define conditions of periodicity.

### 2.3 Imposed normal flow

It is of the conditions of the Neumann type, defining flow entering the field.

$$-\mathbf{q}(r, t) \cdot \mathbf{n} = f(r, t) \quad \text{sur } \Gamma_2$$

where  $f(r, t)$  is a function of the variable of space and/or time and  $\mathbf{n}$  indicate the normal at the border  $\Gamma_2$ .

## 2.4 Exchange

It is of the conditions of the Neumann type modelling the convectifs transfers on the edges of the field.

$$-\mathbf{q}(r, t) \cdot \mathbf{n} = h(r, t)(T_{ext}(r, t) - T(r, t)) \quad \text{sur } \Gamma_3$$

where  $T_{ext}(r, t)$  is a function of the variable of space and/or time representing the temperature of the external medium, and  $h(r, t)$  is a function of the variable of space and/or time representing the coefficient of convectif exchange on the border  $\Gamma_3$ .

## 2.5 Wall exchange

It is of the conditions of the Neumann type bringing into play two pennies left the border in opposite. This kind of boundary condition models a thermal resistance of interface.

$$\begin{aligned} \lambda \frac{\partial T_1}{\partial n_1} &= h(r, t)(T_2(r, t) - T_1(r, t)) \quad \text{sur } \Gamma_{12} & n_1 & \text{ normal external with } \Gamma_{12} \\ \lambda \frac{\partial T_2}{\partial n_2} &= h(r, t)(T_1(r, t) - T_2(r, t)) \quad \text{sur } \Gamma_{21} & n_2 & \text{ normal external with } \Gamma_{21} \\ & & & (n_1 = -n_2 \text{ in general}) \end{aligned}$$

## 2.6 Voluminal source

It is the term  $s(r, t)$  function of the variable of space and/or time.

## 2.7 Initial condition

It is the expression of the field of temperature at the initial moment  $t=0$  :

$$T(r, 0) = T_0(r)$$

where  $T_0(r)$  is a function of the variable of space.

## 3 Variational formulation of the problem

We will restrict ourselves here to present the problem with only the boundary conditions of imposed temperature [§2.1], imposed normal flow [§2.3] or of exchange [§2.4]. The boundary conditions of exchange wall [§2.5] are treated with [the §4] and those with linear relations [§2.2] are brought back without difficulties to that of [§2.1].

That is to say  $\Omega$  open of  $\mathbb{R}^3$ , of border  $\Gamma = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3$ .

The weak formulation of the equation of heat is:

$$\int_{\Omega} \rho C_p \frac{\partial T}{\partial t} \cdot v d\Omega + \int_{\Omega} \lambda \nabla T \cdot \nabla v d\Omega - \int_{\Gamma} \lambda \frac{\partial T}{\partial n} \cdot v d\Gamma = \int_{\Omega} s \cdot v d\Omega$$

where  $v$  is a sufficiently regular function cancelling itself uniformly on  $\Gamma_1$ . With the boundary conditions following:

$$\begin{cases} T = T_1(r, t) & \text{sur } \Gamma_1 \\ \lambda \frac{\partial T}{\partial n} = q(r, t) & \text{sur } \Gamma_2 \\ \lambda \frac{\partial T}{\partial n} = h(r, t)(T_{ext}(r, t) - T) & \text{sur } \Gamma_3 \end{cases}$$

The variational formulation of the problem is:

$$\int_{\Omega} \rho C_p \frac{\partial T}{\partial t} \cdot v d\Omega + \int_{\Omega} \lambda \nabla T \cdot \nabla v d\Omega + \int_{\Gamma_3} h T \cdot v d\Gamma = \int_{\Omega} s \cdot v d\Omega + \int_{\Gamma_2} q \cdot v d\Gamma + \int_{\Gamma_3} h T_{ext} \cdot v d\Gamma$$

## 4 Variational formulation of the problem with condition of exchange between two walls

One considers the "simplified" problem where does not appear any more source term and where the boundary conditions are only of the standard imposed temperature and wall exchanges.

That is to say  $\Omega$  open of  $\mathbb{R}^3$ , of border  $\Gamma = \Gamma_1 \cup \Gamma_{12} \cup \Gamma_{21}$ .

The boundary conditions are in this case:

$$\begin{cases} T = T_1(r, t) & \text{sur } \Gamma_1 \\ \lambda \frac{\partial T_1}{\partial n_1} = h(r, t)(T_2(r, t) - T_1(r, t)) & \text{sur } \Gamma_{12} \\ \lambda \frac{\partial T_2}{\partial n_2} = h(r, t)(T_1(r, t) - T_2(r, t)) & \text{sur } \Gamma_{21} \end{cases}$$

In substituent in the weak formulation of the equation of heat, one obtains:

$$\int_{\Omega} \rho C_p \frac{\partial T}{\partial t} \cdot v d\Omega + \int_{\Omega} \lambda \nabla T \cdot \nabla v d\Omega + \int_{\Gamma_{12}} h(T_{/\Gamma_{12}} - T_{/\Gamma_{21}}) \cdot v d\Gamma_{12} + \int_{\Gamma_{21}} h(T_{/\Gamma_{21}} - T_{/\Gamma_{12}}) \cdot v d\Gamma_{21} = 0$$

where  $v$  cancel yourself uniformly on  $\Gamma_1$ .

This kind of boundary conditions reveals new terms connecting degrees of freedom located on the two borders in relation.

## 5 Discretization in time of the differential equation

A classical way to discretize a first order differential equation consists in using one  $\theta$  - method. Let us consider the following differential equation:

$$\begin{cases} \frac{\partial}{\partial t} y(t) = \varphi(t, y(t)) \\ y(0) = y_0 \end{cases}$$

$\theta$  - method consists in discretizing the equation by a diagram with the finished differences

$$\frac{1}{\Delta t} (y_{n+1} - y_n) = \theta \varphi(t_{n+1}, y_{n+1}) + (1 - \theta) \varphi(t_n, y_n)$$

where  $y_{n+1}$  is an approximation of  $y(t_{n+1})$ ,  $y_n$  being supposed known and  $\theta$  is the parameter of the method,  $\theta \in [0, 1]$ .

**Note:**

if  $\theta = 0$  the diagram is known as explicit,  
if  $\theta \geq 0$  the diagram is known as implicit.

### 5.1.1 Precision of the method

Let us suppose  $y$  sufficient regular (at least 3 times differentiable), by a development of Taylor at the point  $t_n$  one obtains:

$$y(t_{n+1}) - y(t_n) = \Delta t y'(t_n) + \frac{\Delta t^2}{2} y''(t_n) + O(\Delta t^2)$$

and

$$\begin{aligned} \theta \varphi(t_{n+1}, y(t_{n+1})) + (1 - \theta) \varphi(t_n, y(t_n)) &= \theta y'(t_{n+1}) + (1 - \theta) y'(t_n) \\ &= y'(t_{n+1}) + \theta (y'(t_{n+1}) - y'(t_n)) \\ &= y'(t_n) + \theta \Delta t y''(t_n) + O(\Delta t^2) \end{aligned}$$

The solution thus checks roughly:

$$\frac{1}{\Delta t}(y(t_{n+1})-y(t_n)) = \theta \varphi(t_{n+1}, y(t_{n+1})) + (1-\theta)\varphi(t_n, y(t_n)) + \left(\frac{1}{2}-\theta\right)\Delta t y''(t_n) + O(\Delta t^2)$$

The diagram is of order 1 in time if  $\theta \neq \frac{1}{2}$ , and of order 2 if  $\theta = \frac{1}{2}$  (diagram of Crank - Nicolson).

## 5.1.2 Stability of the method

Let us consider the following differential equation:

$$\begin{cases} y' = -\lambda y & t \geq 0 \quad \lambda \in \mathbb{R} \\ y(0) = y_0 \end{cases}$$

While using  $\theta$  - method in this differential equation one obtains:

$$y_{n+1} = \frac{1-(1-\theta)\lambda\Delta t}{1+\theta\lambda\Delta t} y_n \quad 0 \leq n \leq N-1$$

That is to say still:

$$y_{n+1} = r^n(\lambda\Delta t) y_0 \quad \text{avec} \quad r(x) = \frac{1-(1-\theta)x}{1+\theta x}$$

The approximate solution  $y_n$  must be limited (the exact solution of the initial problem being it), which imposes the following condition:

$$|r(\lambda\Delta t)| \leq 1$$

By studying the variations of the function  $r(x)$ , it is noted easily that:

- if  $\theta \geq \frac{1}{2}$  the condition is checked whatever  $\Delta t$ , the diagram is unconditionally stable;
- if  $\theta < \frac{1}{2}$  the condition is checked only if  $\Delta t \leq \frac{2}{\lambda(1-2\theta)}$ , the diagram is conditionally stable.

In the order THER\_LINEAIRE [U4.33.01], the parameter  $\theta$  is a data being able to be provided by the user, the value by default is fixed at 0.57. This value has the reputation to be preferable with the value of Crank - Nicolson (0.5) and "optimal" for the quadratic interpolations, but we did not find trace of the justifications.



## 5.1.3 Application to the equation of heat

Let us use  $\theta$  - method in the variational formulation of the equation of heat, where one posed:

$$\begin{aligned} T^+ &= T(r, t + \Delta t) & T^- &= T(r, t) & h^+ &= h(r, t + \Delta t) & h^- &= h(r, t) \\ f^+ &= f(r, t + \Delta t) & f^- &= f(r, t) & T_{ext}^+ &= T_{ext}(r, t + \Delta t) & T_{ext}^- &= T_{ext}(r, t) \\ s^+ &= s(r, t + \Delta t) & s^- &= s(r, t) & T_1^+ &= T_1(r, t + \Delta t) & T_1^- &= T_1(r, t) \end{aligned}$$

Let us introduce following spaces of functions:

$$\begin{aligned} V_{t^+} &= \left\{ v \in H^1(\Omega) \quad v_{/\Gamma_1} = T_1(r, t^+) \right\} \\ V_{t^-} &= \left\{ v \in H^1(\Omega) \quad v_{/\Gamma_1} = T_1(r, t^-) \right\} \\ V_0 &= \left\{ v \in H^1(\Omega) \quad v_{/\Gamma_1} = 0 \right\} \end{aligned}$$

The field  $T^- \in V_{t^-}$  being supposed known, one seeks  $T^+ \in V_{t^+}$  :

$$\begin{aligned} & \int_{\Omega} \rho C_p \frac{T^+ - T^-}{\Delta t} v d\Omega + \int_{\Omega} (\theta \lambda \nabla T^+ \cdot \nabla v + (1-\theta) \lambda \nabla T^- \cdot \nabla v) d\Omega \\ & - \int_{\Gamma_2} (\theta f^+ + (1-\theta) f^-) v d\Gamma_2 - \int_{\Gamma_3} (\theta h^+ T_{ext}^+ + (1-\theta) h^- T_{ext}^- - \theta h^+ T^+ - (1-\theta) h^- T^-) v d\Gamma_3 \\ & = \int_{\Omega} (\theta s^+ + (1-\theta) s^-) v d\Omega \\ & \forall v \in V_0 \end{aligned}$$

While posing:

$$\begin{aligned} (hT_{ext})^\theta &= \theta h^+ T_{ext}^+ + (1-\theta) h^- T_{ext}^- \\ f^\theta &= \theta f^+ + (1-\theta) f^- \end{aligned}$$

one obtains finally:

$$\begin{aligned} & \int_{\Omega} \frac{\rho C_p}{\Delta t} T^+ v d\Omega + \int_{\Omega} \theta \lambda \nabla T^+ \cdot \nabla v d\Omega + \int_{\Gamma_3} \theta h^+ T^+ v d\Gamma_3 \\ & = \int_{\Omega} \frac{\rho C_p}{\Delta t} T^- v d\Omega - \int_{\Omega} (1-\theta) \lambda \nabla T^- \cdot \nabla v d\Omega + \int_{\Gamma_2} f^\theta v d\Gamma_2 \\ & + \int_{\Gamma_3} ((hT_{ext})^\theta - (1-\theta) h^- T^-) v d\Gamma_3 + \int_{\Omega} (\theta s^+ + (1-\theta) s^-) v d\Omega \\ & \forall v \in V_0 \end{aligned}$$

## 6 Space discretization

That is to say  $P_h$  a space division  $\Omega$ , let us indicate by  $N$  the number of nodes of the grid,  $p_i$  the function of form associated with the node  $i$ . One indicates by  $J$  the whole of the nodes belonging to the border  $\Gamma_1$ .

Are:

$$\begin{aligned} V_{t^+}^h &= \{ v = \sum_{i=1, N} v_i p_i(x) \ ; \ v_j = T_1(x_j, t^+) \ j \in J \} \\ V_{t^-}^h &= \{ v = \sum_{i=1, N} v_i p_i(x) \ ; \ v_j = T_1(x_j, t^-) \ j \in J \} \\ V_0^h &= \{ v = \sum_{i=1, N} v_i p_i(x) \ ; \ v_j = 0 \ j \in J \} \end{aligned}$$

Let us pose:

$$\begin{aligned} K_{ij} T_i &= \int_{\Omega_h} \frac{\rho C_p}{\Delta t} T_i p_i p_j d\Omega_h + \int_{\Omega_h} \theta \lambda T_i \nabla p_i \cdot \nabla p_j d\Omega_h + \int_{\Gamma_{h3}} \theta h^+ T_i p_i d\Gamma_{h3} \\ L_j &= \int_{\Omega_h} \frac{\rho C_p}{\Delta t} T^- p_j d\Omega_h - \int_{\Omega_h} (1-\theta) \lambda \nabla T^- \cdot \nabla p_j d\Omega_h + \int_{\Gamma_{h2}} f^\theta p_j d\Gamma_{h2} \\ &\quad + \int_{\Gamma_{h3}} ((h T_{ext}^\theta)^\theta - (1-\theta) h^- T^-) p_j d\Gamma_{h3} + \int_{\Omega_h} (\theta s^+ + (1-\theta) s^-) p_j d\Omega_h \end{aligned}$$

By dualisant the boundary conditions in imposed temperature ([R3.03.01]), one reveals the operator  $B$  defined by:

$$(Bv)_j = \begin{cases} 0 & \text{si } j \notin J \\ v_j & \text{si } j \in J \end{cases}$$

One obtains finally the following system:

$$\begin{cases} \sum_{i=1}^N K_{ij} T_i + ({}^t B \lambda)_j = L_j & \forall j \\ (BT)_j = T_1(x_j, t) & j \in J \end{cases}$$

## 7 Implementation in Code\_Aster

### 7.1 Introduced equations

The order `THER_LINEAIRE` [U4.33.01] allows to treat the equation in the transitory case such as it is described above, but it also makes it possible to solve the stationary problem which is reduced to the following equation:

$$-\operatorname{div}(\lambda \nabla T) = s \text{ dans } \Omega$$

and boundary conditions following:

$$\begin{cases} T = T_1(r, t_s) & \text{sur } \Gamma_1 \\ \lambda \frac{\partial T}{\partial n} = q(r, t_s) & \text{sur } \Gamma_2 \\ \lambda \frac{\partial T}{\partial n} = h(r, t)(T_{ext}(r, t_s) - T) & \text{sur } \Gamma_3 \end{cases}$$

$t_s$  being the moment taken to evaluate the boundary conditions of the equation.

In the transitory case, it is necessary to provide an initial state, this initial state (field of temperature) can be selected among the following:

- a field which can be uniform or unspecified created by the order `CREA_CHAMP`,
- a field result of a stationary problem describes by the equations above, the moment of calculation is taken at the first moment defined in the list of realities describing the temporal discretization defined by the user,
- a field extracted the result of a transitory problem.

Discretization in time (value of  $\Delta t$ ) must be provided in the shape of one or more lists of moments. These lists are created by the user by the order `DEFI_LIST_REEL` [U4.21.04].

A thermal transient can be calculated by carrying out several calls to the order `THER_LINEAIRE` [U4.33.01] by enriching the same concept of the `evol_ther` type while providing starting from the second call the initial moment by recovery of calculation (to obtain  $T^-$ ) and possibly the final moment.

The fields of temperatures resulting from a calculation contain at the same time the value with the nodes of the grid and the nodes of Lagrange. During a resumption of calculation, it is possible to vary the type of the boundary conditions, the field used to initiate new in-house calculation is then tiny room to the only nodes of the grid. The concept result of the `evol_ther` type will contain fields with the nodes then being based on different classifications. Operators of `Code_Aster` interpolate then only with the nodes of the grid when classification differs.

## 7.2 Principal thermal options calculated in Code\_Aster

### 7.2.1 Boundary conditions and loadings

TEMP_IMPO	DDLI_R DDLI_F	$\int_{\Gamma_1} T^+ \Phi^* d\Gamma_1 + \int_{\Gamma_1} \Phi^0 v dG_1$
	DDLI_R DDLI_F	$\int_{\Gamma_1} \Phi^* T_1 d\Gamma_1$
FLUX_REP	CHAR_THER_FLUN_R CHAR_THER_FLUN_F	$\int_{\Gamma_2} q^0 v dG_2$
EXCHANGE	CHAR_THER_COEF_R CHAR_THER_COEF_F	$\int_{\Gamma_3} \theta h^+ T^+ v d\Gamma_3$
	CHAR_THER_TEXT_R CHAR_THER_TEXT_F	$\int_{\Gamma_3} ((hT_{ext})^0 - (1-\theta)h^- T^-) v d\Gamma_3$
ECHANGE_PAROI	RIGI_THER_PARO_R RIGI_THER_PARO_F	$\int_{\Gamma_{12}} \theta h^+ (T_{/\Gamma_{12}}^+ - T_{/\Gamma_{21}}^+) v_1 d\Gamma_{12}$
	CHAR_THER_PARO_R CHAR_THER_PARO_F	$\int_{\Gamma_{12}} (1-\theta)h^- (T_{/\Gamma_{21}}^- - T_{/\Gamma_{12}}^-) v_1 d\Gamma_{12}$
SOURCE	CHAR_THER_SOUR_R CHAR_THER_SOUR_F	$\int_{\Omega} (\theta s^+ + (1-\theta)s^-) v d\Omega$

### 7.2.2 Calculation of the elementary matrices and transitory term

RIGI_THER	$\int_{\Omega} \theta \lambda \nabla T^+ \cdot \nabla v d\Omega$
MASS_THER	$\int_{\Omega} \frac{\rho C_p}{\Delta t} T^+ v d\Omega$
CHAR_THER_EVOL	$\int_{\Omega} \frac{\rho C_p}{\Delta t} T^- v d\Omega - \int_{\Omega} (1-\theta) \lambda \nabla T^- \cdot \nabla v d\Omega$

## 8 Description of the versions of the document

Version Aster	Author (S) Organization (S)	Description of the modifications
3	J.P. LEFEBVRE (EDF/IMA/MM N)	Initial text